

Square Linear Systems

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E.g.

$$\begin{cases} 3x_1 + 2x_2 = 2 \\ x_1 - x_2 + x_3 = 1 \\ 2x_1 + 3x_3 = 5 \end{cases}$$

$$\begin{array}{ccc} \begin{array}{c} \leftarrow \\ \uparrow \\ A \end{array} & \begin{array}{c} \rightarrow \\ \uparrow \\ X \end{array} & = \begin{array}{c} \rightarrow \\ \leftarrow \\ b \end{array} \\ \text{matrix} & \text{solution} & \leftarrow \text{r.h.s.} \end{array}$$

$$A = \begin{bmatrix} 3 & 2 & 0 \\ 1 & -1 & 1 \\ 2 & 0 & 3 \end{bmatrix} \quad b = \begin{bmatrix} 2 \\ 1 \\ 5 \end{bmatrix}$$

$$A = [m \times n] \quad X = [n \times 1]$$

$$b = [m \times 1]$$

m eqs. , n variables

For a
while

$$m = n$$

$$A x = b$$

$$m = n$$

How many solutions?

- 0 \rightarrow A not invertible, $b \notin \text{Im}(A)$

- 1 \rightarrow A is invertible

$$x = A^{-1} b$$

- ∞ \rightarrow A not invertible, $b \in \text{Im}(A)$

\exists A is not invertible.

$Ax = 0$? how many solutions?

Infinately many solutions

x , λx is also a solution

Back to: $Ax = b$ for non-invertible

$$\left\{ \begin{array}{l} Ax_1 = b \quad \text{has 1 solution} \\ Ax_2 = 0 \quad \text{infinitely} \end{array} \right.$$

$$A(x_1 + x_2) = b$$

$$Ax = b, \quad b \in \text{im}(A)$$

If $b \notin \text{im}(A) \Rightarrow$ no solution

If $b \in \text{im}(A) \Rightarrow$ many solutions

$$Ax = b, \quad A \text{ is invertible}$$

$$\sum_{j=1}^n a_{ij} x_j = b_i \quad \forall i$$

$i=1, \dots, n$

$$x = A^{-1} b$$

NOT how we compute it numerically

Never do $x = \text{inv}(A) * b$

$$\rightarrow \begin{bmatrix} a_{11}^{(1)} & a_{12}^{(1)} & a_{13}^{(1)} \\ a_{21}^{(1)} & a_{22}^{(1)} & a_{23}^{(1)} \\ a_{31}^{(1)} & a_{32}^{(1)} & a_{33}^{(1)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \\ b_3^{(1)} \end{bmatrix}$$

$\frac{a_{21}}{a_{11}}$

Reduced row echelon form

Step 1: Eliminate x_1

a) multiply 1st equation by

$$l_{21} = \frac{a_{21}}{a_{11}}$$

and subtract it from second equations

b) multiply 1st equation by

$$l_{31} = \frac{a_{31}}{a_{11}}$$

eq. # \rightarrow 31 \leftarrow var # a_{11}

and subtract from 3rd eq

$$\left[\begin{array}{c|c|c}
 a_{11} & a_{12} & a_{13} \\
 \hline
 a_{21} - l_{21} a_{11} & a_{22}^{(2)} = a_{22}^{(1)} - l_{21} a_{12} & a_{23}^{(2)} = a_{23}^{(1)} - l_{21} a_{13} \\
 \hline
 \emptyset & a_{32}^{(2)} = a_{32}^{(1)} - l_{31} a_{12} & a_{33}^{(2)} = a_{33}^{(1)} - l_{31} a_{13}
 \end{array} \right]$$

$$\left[\begin{array}{l}
 a_{ij}^{(k+1)} = a_{ij}^{(k)} - l_{ik} a_{kj}
 \end{array} \right]$$

$$l_{ik} = \frac{a_{ik}^{(k)}}{a_{kk}^{(k)}}, \quad i, j > k, \quad a_{kk}^{(k)} \neq 0$$

eq. \nearrow l_{ik} \nearrow $a_{kk}^{(k)}$

$$\begin{bmatrix} b_1^{(1)} \\ b_2^{(1)} \\ b_3^{(1)} \end{bmatrix} \rightarrow \begin{bmatrix} b_1^{(2)} = b_1^{(1)} \\ b_2^{(2)} = b_2^{(1)} - l_{21} b_1^{(1)} \\ b_3^{(2)} = b_3^{(1)} - l_{31} b_1^{(1)} \end{bmatrix}$$

$$b_i^{(k+1)} = b_i^{(k)} - l_{ik} b_k^{(k)}$$

Step 2

$$\begin{bmatrix} a_{11}^{(1)} & a_{12}^{(1)} & a_{13}^{(1)} \\ l_{21} & a_{22}^{(2)} & a_{23}^{(2)} \\ l_{31} & a_{32}^{(2)} & a_{33}^{(2)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1^{(2)} \\ b_2^{(2)} \\ b_3^{(2)} \end{bmatrix}$$

Multiply 2nd eq. by

$$l_{32} = \frac{a_{32}^{(2)}}{a_{22}^{(2)}}$$

↑ ↑
eq. var

and subtract from 3rd eq.

$$\begin{bmatrix} a_{11}^{(1)} & a_{12}^{(1)} & a_{13}^{(1)} \\ l_{21} \phi & a_{22}^{(2)} & a_{23}^{(2)} \\ l_{31} \phi & l_{32} \phi & a_{33}^{(3)} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1^{(1)} \\ b_2^{(2)} \\ b_3^{(3)} \end{bmatrix}$$

Step 3 :

$$x_3 = \frac{b_3^{(3)}}{a_{33}^{(3)}}$$

Step 4:

$$x_2 = \frac{b_2^{(2)} - a_{23}^{(2)} x_3}{a_{22}^{(2)}}$$

Step 5: solve for x_1

Gaussian elimination

$$L = \begin{bmatrix} 1 & & & & \\ \hline l_{21} & 1 & & & \\ \hline l_{31} & l_{32} & \ddots & & 1 \end{bmatrix}$$

$\det(L) = 1$
is
invertible

unit lower triangular matrix

$$U = \begin{bmatrix} a_{11}^{(1)} & a_{12}^{(1)} & a_{13}^{(1)} \\ \emptyset & a_{22}^{(2)} & a_{23}^{(2)} \\ \emptyset & \emptyset & a_{33}^{(3)} \end{bmatrix}$$

Upper triangular

Theorem: $A = LU$

LU factorization

\Leftrightarrow Gauss elimination

Code MyLU.m on
webpage

$$\bar{i} > k : l_{ik} = \frac{a_{ik}}{a_{kk}} \Rightarrow a_{ik}$$

$$l_{kk} = 1 \quad (\text{not stored})$$

for $k = 1 : (n-1)$
Eliminate x_k from
eqs. $k+1, \dots, n$

$$A((k+1):n, k) =$$

$$A((k+1):n, k) / A(k, k);$$

compute $l_{ik}, \bar{i} > k$

$$a_{ij} \leftarrow a_{ij} - l_{ik} a_{kj}$$

$$i, j > k$$

for $j = (k+1) : n$

$$A((k+1):n, j) = A((k+1):n, j)$$

$$- A((k+1):n, k) * A(k, j);$$

stores l_{ik}

"in-place"

end [for j]

LU

factorization

end [for k]

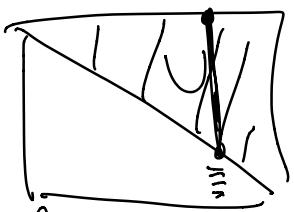
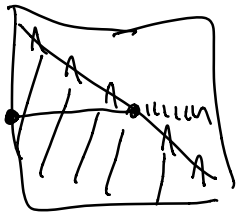
Note We could have done
for $i = (k+1) : n$

Last time: $Ax = b$

GEM: $A = LU$
 \uparrow lower \uparrow upper \uparrow trans.

"Proof":
 $a_{ij} = \sum_{k=1}^n l_{ik} u_{kj}$

Dot product between i 'th row of L and j 'th column of U



$a_{ij} = \sum_{k=1}^{\min\{i,j\}} l_{ik} u_{kj}$

If $i > j \Rightarrow \sum_{k=1}^j$

If $i \leq j \Rightarrow \sum_{k=1}^i$

Recall $l_{ii} = 1$

$$\begin{aligned}
 \textcircled{1} \quad a_{ij} &= \sum_{k=1}^i l_{ik} u_{kj} \\
 &= \sum_{k=1}^{i-1} l_{ik} u_{kj} + u_{ij}
 \end{aligned}$$

$l_{ii} = 1$

$$\Rightarrow u_{ij} = a_{ij} - \sum_{k=1}^{i-1} l_{ik} u_{kj}$$

\checkmark
 GEM

We need l_{ik} and $u_{(k < i), j}$

$$a_{ij}^{(k+1)} = a_{ij}^{(k)} - l_{ik}^{(k)} \cdot a_{kj}^{(k)}$$

②

$$a_{\bar{i}j} = \sum_{k=1}^j l_{\bar{i}k} u_{kj}$$

$\bar{i} > j$

$$l_{\bar{i}j} = \frac{(a_{\bar{i}j} - \sum_{k=1}^{j-1} l_{\bar{i}k} u_{kj})}{u_{jj}}$$

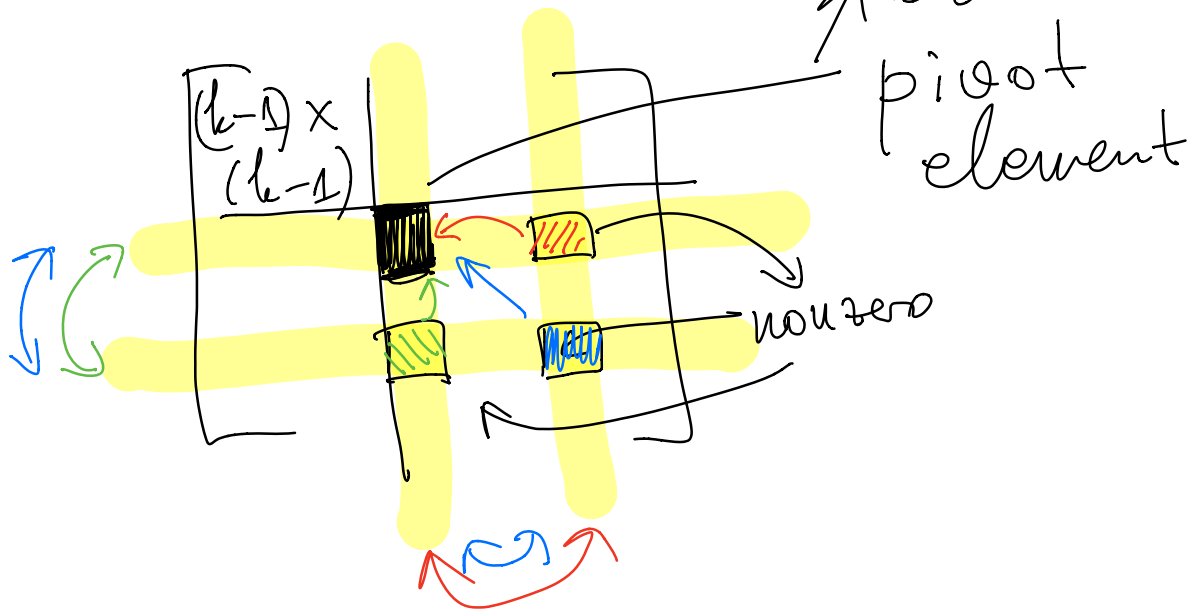
$$l_{\bar{i}j} = \frac{a_{\bar{i}j}^{(j)}}{u_{jj}^{(j)}}$$

Which shows that GEM
computed L & U s.t.

$$A = LU$$

Pivoting

Assumed that $a_{hh}^{(k)} \neq 0$



Pivoting: Row, Column,
Complete = Row + column

Let's re-order equations

$$\begin{matrix} 2 \times \\ 3 \times \end{matrix} \begin{bmatrix} 1 & 1 & 3 \\ 2 & 2 & 2 \\ 3 & 6 & 4 \end{bmatrix} \begin{bmatrix} x_1 = 1 \\ x_2 = 1 \\ x_3 = 1 \end{bmatrix} = \begin{bmatrix} 5 \\ 6 \\ 13 \end{bmatrix}$$

\Downarrow

$$\begin{bmatrix} 1 & 1 & 3 \\ 0 & 0 & -4 \\ 0 & 3 & -5 \end{bmatrix} \Rightarrow \begin{bmatrix} 5 \\ -4 \\ -2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & 3 \\ 0 & 3 & -5 \\ 0 & 0 & -4 \end{bmatrix} \begin{bmatrix} x_1 = 1 \\ x_2 = 1 \\ x_3 = 1 \end{bmatrix} = \begin{bmatrix} 5 \\ -2 \\ -4 \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & & \\ 2 & 1 & \\ 3 & 0 & 1 \end{bmatrix}$$

$$LU = \underline{P} A$$

\uparrow permutasi
matrix

Theorem :

If A is non-singular
then pivoted LU factorization
will succeed

$$PA = LU$$

for some permutation
matrix P

What is the best P

Example :

$$\left[\begin{array}{cc|c} 10^{-20} & 1 & \\ \hline 1 & 1 & \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$x_1 \approx x_2 \approx 1$$

||

$10^{20} \times$ \Downarrow GEM

$$\left[\begin{array}{c|c} 10^{-20} & 1 \\ \hline \emptyset & 1 - 10^{20} \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 - 10^{20} \end{bmatrix}$$

Due to roundoff

$$\left[\begin{array}{c|c} 10^{-20} & 1 \\ \hline & -10^{20} \end{array} \right] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ -10 \end{bmatrix}$$

$$x_2 = \frac{-10^{20}}{-10^{20}} = \underline{1} \quad \checkmark$$

$$10^{-20} x_1 = \underline{1} - \underline{1} = 0$$

$$\Rightarrow x_1 = 0 \neq \underline{1} \quad \times$$

Not the correct solution

$$\begin{bmatrix} 1 & 1 \\ 10^{-20} & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 \\ \emptyset & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$x_1 = x_2 = 1 \quad \checkmark$$

Or change order of variables

$$\begin{bmatrix} 1 & 10^{-20} \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_2 \\ x_1 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

"Small" pivot elements are a problem in floating-point arithmetic

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & \cancel{9} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 1 \\ \cancel{0} \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 8 & \cancel{9} \\ 4 & 5 & 6 \\ 1 & 2 & 3 \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix} = \begin{bmatrix} 2 \\ \cancel{0} \\ 1 \end{bmatrix}$$

$$\begin{bmatrix} 7 & 8 & 0 \\ 0 & \frac{3}{7} & 6 \\ 0 & \frac{6}{7} & 3 \end{bmatrix} \begin{bmatrix} \\ \\ \end{bmatrix} = \begin{bmatrix} 2 \\ -8/7 \\ 5/7 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 7 & 8 & 0 \\ 0 & 6/7 & 3 \\ 0 & 3/7 & 6 \end{bmatrix} \dots \begin{bmatrix} 2 \\ 5/7 \\ -8/7 \end{bmatrix}$$

\Downarrow

$$\begin{bmatrix} 7 & 8 & 0 \\ 0 & 6/7 & 3 \\ 0 & 0 & 9/2 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 5/7 \\ -3/2 \end{bmatrix}$$

$$P^{-1} \mid \underline{P} A = L U = \underline{P} b$$

$$P^{-1} = P^T$$

$$A = P^T L U = b$$

$$A = (P^T L) U = \tilde{L} U$$

\uparrow

$$\begin{array}{l}
 1 \\
 2 \\
 3
 \end{array}
 \begin{bmatrix}
 D & & \\
 D & D & \\
 D & D & D
 \end{bmatrix}
 \qquad
 \begin{array}{l}
 \text{permuted lower} \\
 \text{triangular} \\
 3 \\
 2 \\
 1
 \end{array}
 \begin{bmatrix}
 D & D & D \\
 D & D & \\
 D & &
 \end{bmatrix}$$

In MATLAB :

$$Ax = b$$

$$L(UX) = b$$

① $L y = b$ *forward subst.* to get y

② $U x = y$ *backward substitution* for x

$$\begin{bmatrix} l_{11} & & \\ l_{21} & l_{22} & \\ \vdots & \vdots & \ddots \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ \vdots \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \end{bmatrix}$$

$$l_{11} y_1 = b_1 \Rightarrow$$

$$y_1 = b_1 / l_{11} = 1 = b_1$$

$$y_2 = \frac{b_2 - l_{21} y_1}{l_{22} = 1}$$

$$Ly = b$$

$$y_i = \frac{b_i - \sum_{j=1}^{i-1} l_{ij} y_j}{l_{ii} = 1}$$

$$i = 1, \dots, n$$

Matlab code

```
for i = 1 : n  
y(i) = b(i) - sum(L(i, 1:i-1) .*  
y(1:i-1))  
end
```

Forward
substitution

For $Ux = y$ (Backward)
for $i = n : -1 : 1$
Homework

Matlab syntax "mldivide"

$[L, U, P] = \text{lu}(A)$
is really \tilde{L}
 $y = \tilde{L} \setminus b$; % Solve $Ly = b$
 $x = U \setminus y$; % Solve $Ux = y$

intent →

equiv To solve $A * x = b$ in Matlab

$$\{ x = A \backslash b ;$$

"ml divide"

Different from $x = inv(A) * b$

never do this

Equivalent:

$$x = U \backslash (L \backslash b);$$

P is hidden

important

Things we care about:

→ **Convergence** (?)
(consistent, stable)

→ Speed of convergence
(order of accuracy)

→ **Robustness**

↙ opposition

→ **Roundoff error** (stability, error propagation)
(Backward stability)

→ **Efficiency** (computational complexity)

Complexity of LU fact.

FLOPS = floating

point operations

+ , - , * , /

Backward / forward substitution

for $i = 1 : n$
 $y(i) = b(i) - \text{sum}(L(i, 1:i-1) \cdot y(1:i-1))$

end

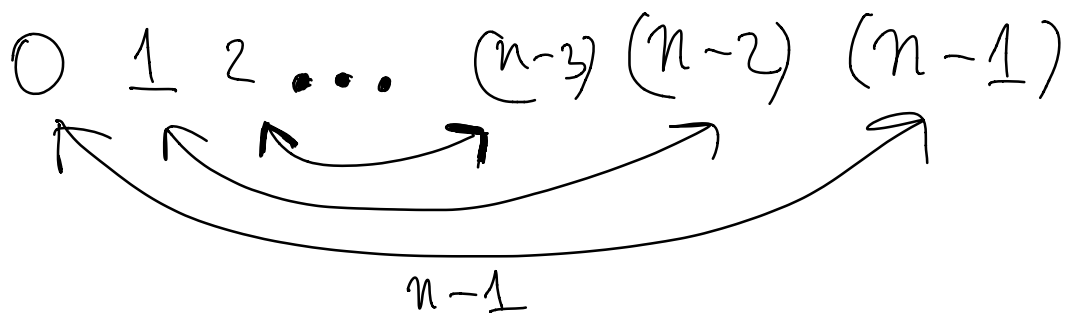
$L(i, 1:i-1) \cdot y(1:i-1)$
dot product

$i-1$ multiplications (elementwise)

$1 + i - 2$ additions

$2 * (i - 1)$ FLOPS

$2 \sum_{i=1}^n (i-1) = \frac{n(n-1)}{2}$



$$\# \text{ FLOPS} = n(n-1) \approx n^2 - \text{Small}$$

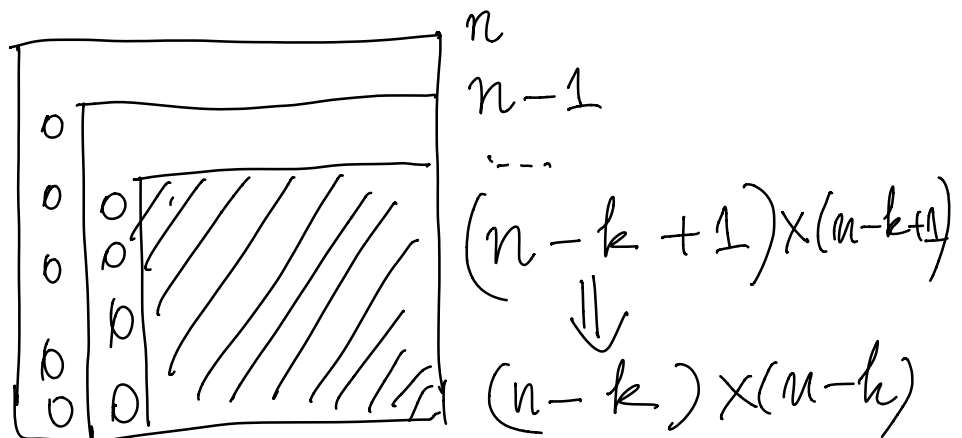
Forward / backward subst.

takes $\sim n^2$ FLOPS

$O(n^2)$ operations



LU factorization cost



Step k takes $O((n-k)^2)$

FLOPs (coefficient in
worksheet 3)

$$\sum_{k=1}^{n-1} (n-k)^2 = \sum_{k=1}^{n-1} k^2$$

$$= \left\{ \begin{array}{l} \int_{k=1}^n k^2 dk \sim \frac{n^3}{3} \\ a_3 n^3 + a_2 n^2 + a_1 n + a_0 \end{array} \right.$$

correct
leading-order
term

LU factorization takes

$$O(n^3) \text{ FLOPs} \gg O(n^2)$$

All matrix factorizations

$$\sim O(n^3)$$

Stability of problems

$$Ax = b$$

$$(A + \delta A)(x + \delta x) = \underline{b + \delta b}$$

$$\frac{\|\delta A\|}{\|A\|} \geq 10^{-16}$$

$$\frac{\|\delta b\|}{\|b\|} \geq 10^{-16}$$

Question $\frac{\|\delta x\|}{\|x\|} = ?$

$$\frac{\|\delta x\|}{\|x\|} \leq K(A) \frac{\|\delta b\|}{\|b\|}$$

conditioning number

$$K(A) = \|A\| \|A^{-1}\|$$

(depends on choice of norm)

$$X \longrightarrow AX$$

$$X + \delta X \xrightarrow{K(A)} AX + ?$$

relative change

E.g. $K(A) = 10^4$

$$6 \text{ digits } m \times \rightarrow 6 - 4 = 2 \text{ digits } m \times AX$$

Our case

$$X \longrightarrow A^{-1}b$$

$$b \longrightarrow A^{-1}b$$

$$K(A^{-1}) = \|A^{-1}\| \|(A^{-1})^{-1}\|$$

$$K(A^{-1}) = K(A) = (\|A\| \|A^{-1}\|)$$

$$\frac{\|\delta x\|}{\|x\|} \geq \epsilon \cdot K(A)$$

ϵ
 10^{-16}

$K(A) = 10^p$ means loose p digits

$p \gg 1$ ill-conditioned matrix/system

Most of the time, pivoted LU factorization gives us this accuracy (does not lose extra digits)

$$Ax = b$$

$$\|Ax - b\| = 0$$

$$r = Ax - b$$

Always check solution
by computing $\|r\| = \|Ax - b\|$

$$\frac{\|r\|}{\|b\|} \sim 10^{-16}$$

We really want this
backwards stability.

"Theorem": Pivoted LU is
backwards stable

More precisely:

$$x = A \setminus b$$

$$(A + \delta A) x = b + \delta b$$

$$\frac{\|\delta A\|}{\|A\|} \sim \frac{\|\delta b\|}{\|b\|} \sim 10^{-16}$$