

Solving systems of non-linear eqs.

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$$\left\{ \begin{array}{l} f_1(x_1, x_2) = 0 \\ f_2(x_1, x_2) = 0 \end{array} \right. \quad \left\{ \begin{array}{l} \underline{f(x, y)} = 0 \\ \underline{g(x, y)} = 0 \end{array} \right.$$

$$\begin{array}{ccc} x_1^{(k)} & & x_1^{(k+1)} \\ x_2^{(k)} & \rightarrow & x_2^{(k+1)} \end{array}$$

No bisection in higher dims.

(real numbers are ordered)

$$f_{\perp}(x_1, x_2) = f(x_1^{(h)}, x_2^{(h)})$$

$$+ \frac{\partial f_1}{\partial x_1} (x_1 - x_1^{(h)})$$

$$+ \frac{\partial f_2}{\partial x_2} (x_2 - x_2^{(h)}) + O\left(\frac{|x_1 - x_1^{(h)}|}{2}\right) + O(\text{squared})$$

$$\vec{f} = [f_1, f_2]^T$$

$$\vec{f} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$$

$$\vec{x} = (x_1, x_2)^T$$

$$\vec{f}(\vec{x}) : \vec{x} \in \mathbb{R}^2 \rightarrow \vec{f} \in \mathbb{R}^2$$

$$\vec{f}(\vec{x}^{(h+1)}) = \vec{f}(\vec{x}^{(h)}) + \begin{bmatrix} \partial f_1 / \partial x_1 & \partial f_1 / \partial x_2 \\ \partial f_2 / \partial x_1 & \partial f_2 / \partial x_2 \end{bmatrix} \begin{bmatrix} x_1^{(h+1)} - x_1^{(h)} \\ x_2^{(h+1)} - x_2^{(h)} \end{bmatrix}$$

$\vec{J}(\vec{x})$ - Jacobian matrix

$$J_{ij} = \frac{\partial f_i}{\partial x_j}$$

$$\vec{f}(\vec{x}^{(h+1)}) = \vec{f}(\vec{x}^{(h)}) + \vec{J}(\vec{x}^{(h)}) \cdot (\vec{x}^{(h+1)} - \vec{x}^{(h)})$$

$$\overrightarrow{\Delta X} = X^{(k+1)} - X^{(k)}$$

$$f(X^{(k+1)}) = 0$$

$$f^{(k+1)} = f^{(k)} + J^k \Delta X^k = 0$$

$$J^k \Delta X^k = -f^{(k)}$$

linear system (LU)

$$X^{k+1} = X^k + \underline{\Delta X^k}$$

~~$$X^{k+1} = X^k - (J^k)^{-1} f^{(k)}$$~~

on paper
(use backslash / LU)

$$\|Ax\| \leq \|A\| \|x\|$$

When to stop?

Termination or stopping criterion

Two options:

① Stop if $\|f^k\|_{1,2,\infty} < \epsilon$

↑
tolerance
↓

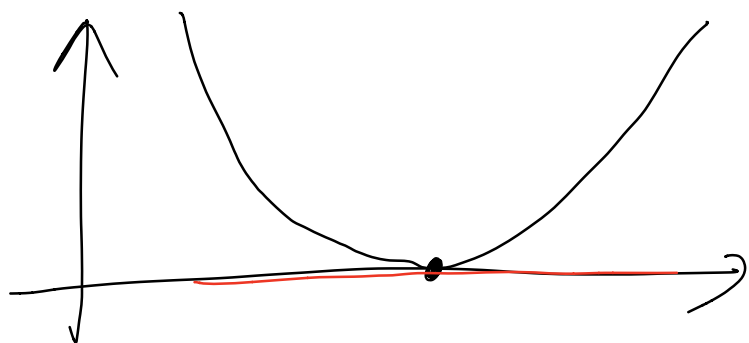
② Stop if $\|\Delta x^k\|_{1,2,\infty} < \epsilon$

Options are related but not the same

Option 2: $\|(\mathcal{J}^k)^{-1} f^k\| < \epsilon$

estimate $\|(\mathcal{J}^k)^{-1}\| \|f^k\| < \epsilon$

$\|f^k\| < \epsilon / \|(\mathcal{J}^k)^{-1}\|$



Second-order Taylor series

$$f: \mathbb{R}^n \rightarrow \mathbb{R}$$

$$f(\vec{x} + \Delta\vec{x}) = f(\vec{x})$$

$$+ \underbrace{\vec{g}^T}_{\text{scalar}} \Delta\vec{x} + \frac{1}{2} \underbrace{(\Delta\vec{x})^T}_{\text{vector}} \underbrace{H(\Delta\vec{x})}_{\text{vector}}_{\text{scalar}}$$

$$\vec{g} = \vec{J}^T = \text{gradient (column vector)}$$

$$+ \mathcal{O}(\|\Delta\vec{x}\|^3)$$

$$H_{ij} = \frac{\partial^2 f}{\partial x_i \partial x_j} = H_{ji}$$

Hessian matrix
Symmetric

(Cholesky factorization instead
of LU)

Convergence of Newton's
method

$$x^{(k+1)} = x^{(k)} - (J^{(k)})^{-1} f^{(k)}$$

$$e^{(k)} = x^{(k)} - x^*, \quad f(x) = 0$$

$$\|e^{(k+1)}\| \stackrel{?}{\longleftrightarrow} \|e^{(k)}\|$$

$$\begin{aligned}
 \vec{f}(\vec{x}^k) &= f(x) + J e^k \\
 &+ \frac{1}{2} (\vec{e}^k)^T \overset{\leftrightarrow}{H} (\vec{e}^k) \\
 &+ O(\|e^k\|^3)
 \end{aligned}$$

\vec{e}^k scalar vector
 H rank-3 tensor
 (supported in Matlab)

$$J = J(x)$$

$$H = H(x)$$

$$\begin{aligned}
 \underbrace{x^{k+1} - x^k}_{\vec{e}^k} &= e^{k+1} = \\
 \underbrace{(x^k - x)}_{\vec{e}^k} &= J^{-1} f(x^k)
 \end{aligned}$$

$$= e^k - J^{-1} \underbrace{f(x^h)}_{\text{plug in Taylor series}}$$

$$= e^k - J^{-1} \left[\cancel{f(x)} + \underline{J e^k} + \frac{1}{2} (e^h)^T H (e^h) + O(\|e^h\|^3) \right]$$

$$e^{k+1} = - \frac{J^{-1}}{2} (e^h)^T H (e^h)$$

$$\|e^{k+1}\| \leq \frac{1}{2} \|e^k\|^2 \|H\| \|J^{-1}\|$$

$$\|e^{k+1}\| \leq \frac{1}{2} \|H\| \|J^{-1}\| \|e^k\|^2$$

quadratic convergence

$$e^{k+1} \approx -\frac{1}{2} \frac{f''(x)}{f'(x)} (e^k)^2$$

If Newton's method converges,
it will converge fast
(quadratically)

Requires a good initial guess

Efficient but NOT robust